# Functions we need:

* Check the connection of Yumi (Not able to do it)
* Connect the Yumi
* Print log
* Check the connection of laser
* Connect the laser
* Move the Yumi to default position (initial position)
* Read position data from a position table (Can be Default or list that input by user)
* Move end-effector (laser) to specific position
* Resample function for resample positions data in the table
* 3D reconstruction algorithm
* Plot 3D graph using data from table and result of 3D reconstruction algorithm
* Add new position value to a position table
* Save the reading data from laser to a file (maybe .txt)
* Load the laser data from a file (maybe .txt)
* Small movement of Yumi (x, y, z axis)
* Get the x,y,z, and distance from end-effector and display them

Variables:

* Default table: a position table for Yumi movements for known geometry. (values: x, y, z)
* My list table: a position table made by user (values: x,y,z)
* Laser data: (x, y, z, distance).

We need distance for keep the distance between laser and the geometry surface.